

SIMULATION TOOLS FOR STATISTICAL MODEL COMPARISON: AN APPLICATION TO UNOBSERVED COMPONENT MODELS VERSUS DYNAMIC REGRESSION MODELS

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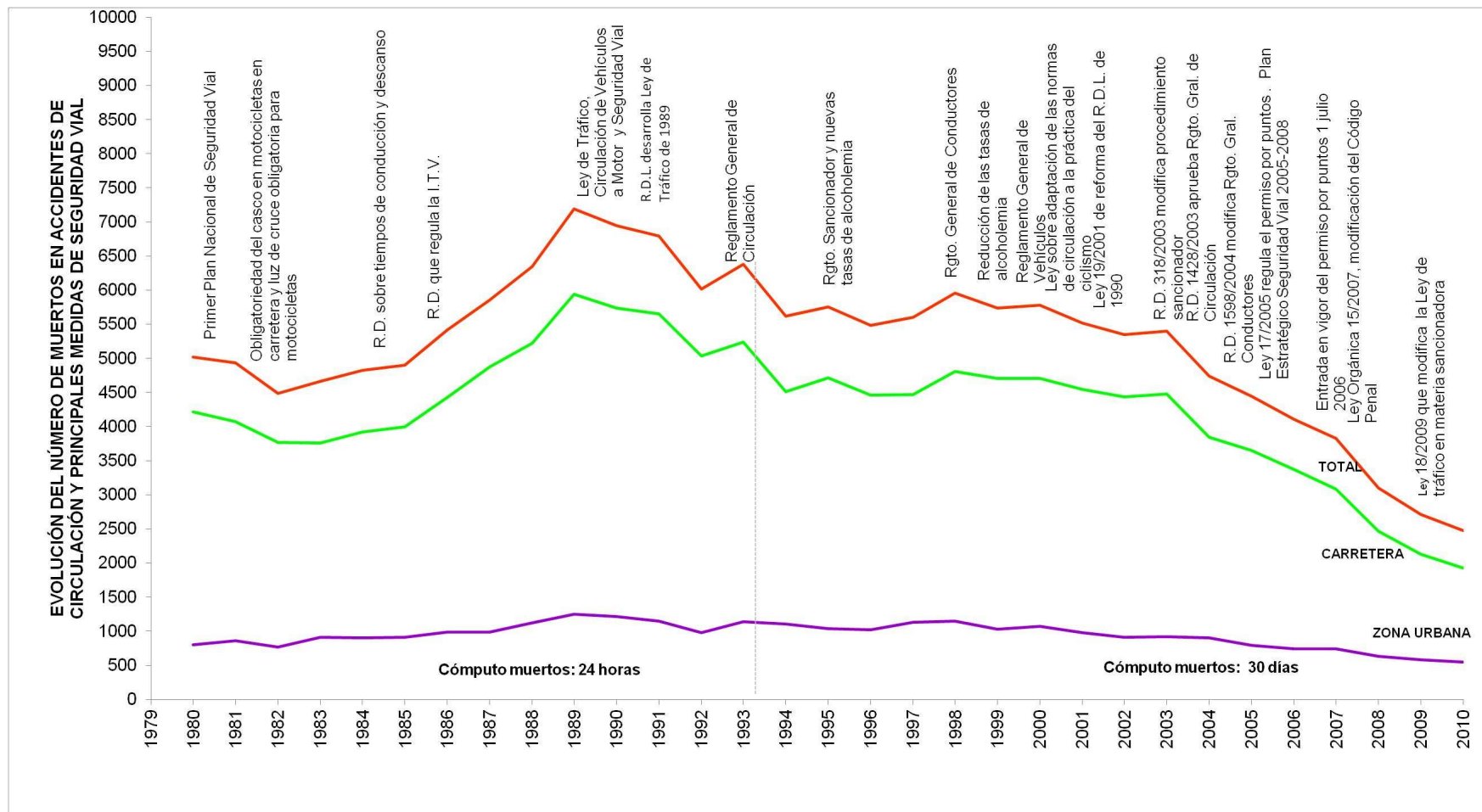
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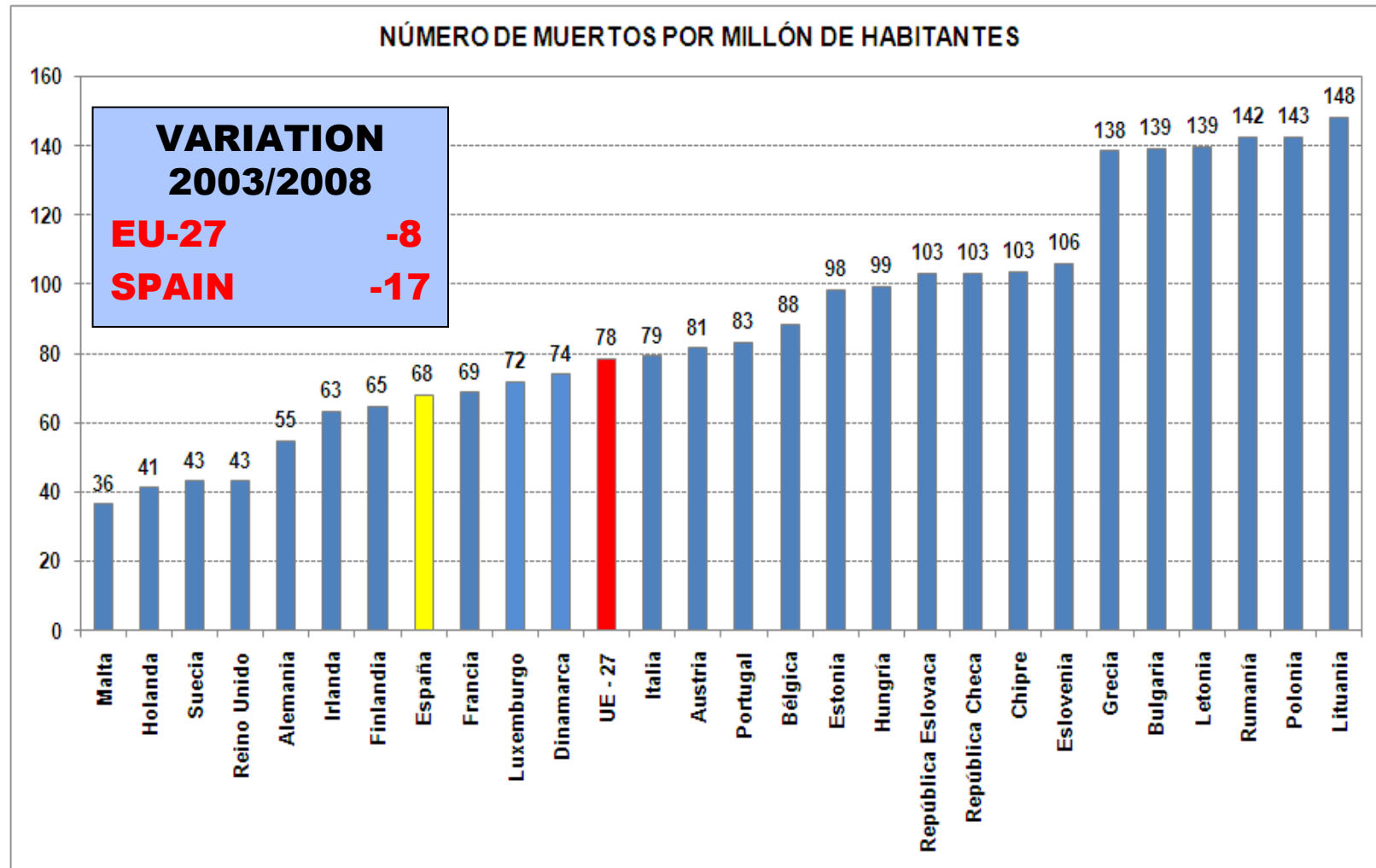
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ROAD ACCIDENTS IN SPAIN

FATALITY RATE IN SPANISH ROADS-LEGISLATIVE CHANGES



ROAD ACCIDENTS IN SPAIN



DYNAMIC MACRO MODELS FOR ROAD ACCIDENT ANALYSIS

- ❑ Tool to quantify the effects mentioned above mainly two time series model are used:
 - Demand for road use, accidents and their gravity (DRAG), developed by Gaudry (1984) and Gaudry and Lassarre (2000) ;
 - Unobserved Components Models (UCM) with intervention proposed by Harvey and Durbin (1986).

- ❑ Main differences
 - UCM includes unobserved specific terms for *trend* and *seasonality*
 - State equations for both terms
 - UCM more complex and general
 - DRAG has simpler interpretation

Question:

Relationship between two models, which DRAG terms capture UC trend and seasonality?

PURPOSE

- ❑ Better understanding of relationship between the two “competing” models
- ❑ We suppose UC is the true model and:
 - ✓ See how the DRAG parameter estimates capture the UC terms.
 - ✓ Relationship between parameters of both models.
 - ✓ Eventually effect on prediction as well.

STAGES OF COMPUTATIONAL EXPERIMENT

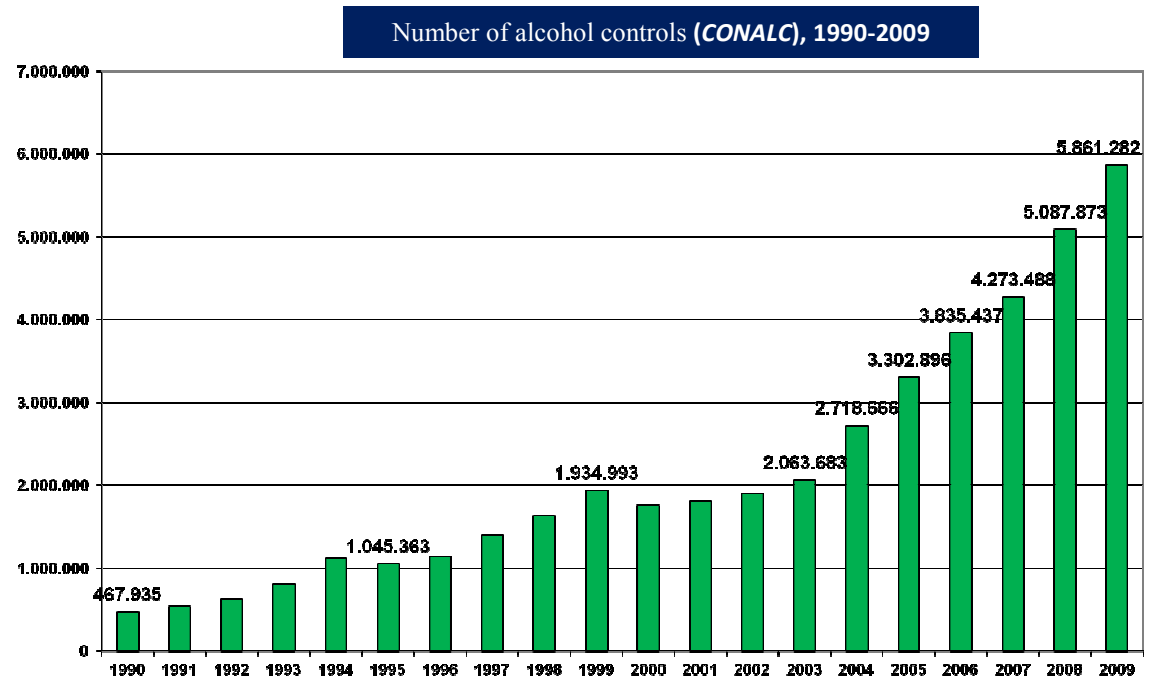
□ The experiment is a **simulation** study with the following steps:

- ✓ *Designing the simulations of the UC model using the results of the empirical study*
- ✓ *Generation of UC samples (time series)*
- ✓ *DRAG estimation:*
- ✓ *ANOVA-type analysis of results*

INPUT VARIABLES

Table 1. Input variables

VARIABLES		
Exposure	Total fuel consumption	<i>COMTOT</i>
Economic factors	Unemployment rate in service sector	<i>PARSER</i>
Driver behavior	Number of alcohol control	<i>CONALC</i>
	Driver license suspension	<i>SUSP</i>
Labor conditions	Number of labor days	<i>DLAB</i>



STAGES OF COMPUTATIONAL EXPERIMENT: UC MODEL TO BE SIMULATED

The state space model consists of :

Measurement equation :

$$y_t = \mu_t + \sum_{j=1}^k \delta_j x_{jt} + \omega_t + \varepsilon_t$$

State equation :

$$\mu_t = \mu_{t-1} + \eta_t$$

where ε_t and η_t are i.i.d $(0, \sigma_{\varepsilon_t})$ and $(0, \sigma_{\eta_t})$ respectively. And ω_t is an intervention variable

$$\omega_t = \begin{cases} 1 & \text{if } t < \tau \\ 0 & \text{if } t \geq \tau \end{cases}$$

[Go back](#)

Table 2. Input factors and the UCM estimators obtained from empirical work

UCM PARAMETERS –INPUT FACTORS		ESTIMATORS (t-value)
REGRESSORS	δ_{PARSER}	0.97 (4.3)
	δ_{CONALC}	-0.24 (-2.43)
	δ_{SUSP}	-0.38 (-6.83)*
	δ_{DLAB}	-0.31 (-2.63)
	δ_{COMTOT}	2.03 (4.3)
TC VARIANCE	σ_{η_t}	0.02

Simulation model using the parameters in Table 2.:

$$y_t = \mu_t + \delta_{PARSER} x_{1t} + \delta_{CONALC} x_{2t} + \delta_{SUSP} x_{3t} + \delta_{DLAB} x_{4t} + \delta_{COMTOT} x_{5t} + \omega_{LCP} + \varepsilon_t$$

$$\omega_t = \begin{cases} 1 & \text{if } t < 96 \\ 0 & \text{if } t \geq 96 \end{cases}$$

STAGES OF COMPUTATIONAL EXPERIMENT: DRAG MODEL TO BE ESTIMATED

The general DRAG model is specified as follows :

$$Y_t^{(\lambda_y)} = \sum_{k=1}^K \beta_k X_t^{(\lambda_{xk})} + u_t$$

where u_t follows and $AR(l)$ process :

$$u_t = \sum_{l=1}^r \rho_l u_{t-l} + w_t$$

and the model variables are BCT :

$$Y_t^{(\lambda_y)} = \begin{cases} \frac{Y_t^{\lambda_y} - 1}{\lambda_y}, & \text{if } \lambda_y \neq 0 \\ \ln(Y_t), & \text{if } \lambda_y = 0 \end{cases}$$

Table 3. Response parameters

DRAG PARAMETERS	
REGRESSORS	β_{PARSER}
	β_{CONALC}
	β_{SUSP}
	β_{DLAB}
	β_{COMTOT}
AR PARAMETERS	ρ_1
	ρ_2
BCT COEFFICIENT	λ

- ☐ The DRAG model is estimated using TRIO which is developed by Lassarre and Gaudry ()
- ☐ DRAG parameters were estimated using :
 - ☐ Same independent variables as in UC;
 - ☐ Errors follow an autoregressive model of order 2.
- ☐ 8 response parameters in total

[Go back](#)

STAGES OF COMPUTATIONAL EXPERIMENT: EXPERIMENTAL DESIGN

Figure1: Experimental design

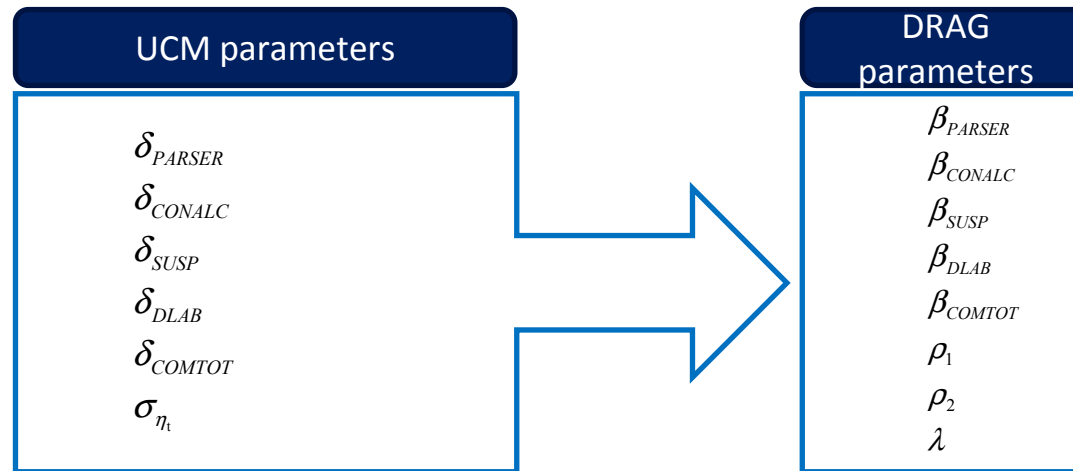


Table 4. Design matrix “+” and “-” for high and low levels of variables.

	δ_{PARSER}	δ_{CONALC}	δ_{SUSP}	δ_{DLAB}	...	
o	-	-	-	-	...	-0.341
δ_{PARSER}	+	-	-	-	...	-0.341
δ_{CONALC}	-	+	-	-	...	-0.306
δ_{SUSP}	-	-	+	-	...	-0.341
δ_{DLAB}	-	-	-	+	...	-0.341
...

STAGES OF COMPUTATIONAL EXPERIMENT: ANOVA ANALYSIS

- Estimation of main effects and interactions (2nd, 3rd, 4th, 5th and 6th order) with the Yates algorithm:

$$\overline{\delta_1} = \frac{1}{4n} (-1 + \delta_1 - \delta_2 - \delta_3 - \delta_4 - \dots)$$

$$\overline{\delta_1 \delta_2} = \frac{1}{4n} (1 - \delta_1 - \delta_2 + \delta_3 + \dots + \delta_1 \delta_2 + \dots)$$

- Computation of ANOVA - sums of squares

$$SS_{\delta_1} = \frac{1}{8n} (-1 + \delta_1 - \delta_2 - \delta_3 - \delta_4 + \dots)^2$$

$$SS_{\delta_1 \delta_2} = \frac{1}{8n} (1 - \delta_1 - \delta_2 + \delta_3 + \dots + \delta_1 \delta_2 + \dots)^2$$

- ANOVA F-tests were applied to test their significance.
- We neglect interactions of 5th and 6th order, to estimate the error variance.

RESULTS AND INTERPRETATION

Table 5. Experimental design results for β_{CONALC} (considering up to 4th interaction effects only)

Variable	Effect estimate	Sum of squares	DF	Mean square	F-test	P-value
σ_{η_t}	0.1399	0.3133	1	0.3133	72.88889	<0.0001
$\delta_1 \delta_{CONALC} \delta_3 \delta_5$	-0.1216	0.2364	1	0.2364	55.00376	<0.0001
δ_{CONALC}	0.0919	0.1351	1	0.1351	31.41867	0.0001
...
Error	0.0301		7			
Total	1.4820		63			
R^2	0.9797					

- ❑ This model explains 97% of the variability in the total model, F -test is significant.
- ❑ For response β_{CONALC} , the most significant effects and interactions:
 - ✓ Trend variance, (σ_{η_t})
 - ✓ Second UCM regression coefficient, (δ_{CONALC})

CONCLUSIONS

- ❑ Results are as expected intuitively, the trend effect has more complex interpretation. The DRAG regression coefficient is capturing :
 - ✓ the change in the corresponding UCM coefficient,
 - ✓ as well as the change in the variance of the trend component!
- ❑ Future research:
 - ❑ Effect on prediction errors
 - ❑ MANOVA instead of individual ANOVAs
 - ❑ Regression models including only significant effects and interactions.
 - ❑ In deterministic versus stochastic trend analysis

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